

Resource analysis by Sup-interpretations

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Motivations

Develop a criterion to bound the size of the stack frames computed by a program which terminates or not:

- Dependency pairs method (Arts et Giesl 96)
- the notion of **sup-interpretation** distinct from the one of quasi-interpretation (Bonfante, Moyen, Marion 00):
 - It ranges over a part of the set of function symbols
 - A relaxed subterm property
- Static analyse
- Practical issues : Computer security
- It applies to functional first order programs

First order Language: syntax

Constructors: \mathcal{C} , Operators: Op , functions: \mathcal{F} , variables: \mathcal{X} .

(Terms) $\ni t ::= x \mid \mathbf{c}(t_1, \dots, t_n) \mid \mathbf{f}(t_1, \dots, t_n)$
 $\mid \mathbf{Case} \bar{e} \text{ of } \bar{p}_1 \rightarrow e^1, \dots, \bar{p}_l \rightarrow e^l$
 $\mid \mathbf{op}(e_1, \dots, e_n)$

(Patterns) $\ni p ::= \mathbf{c}(p_1, \dots, p_n) \mid x$

(Definitions) $\ni d ::= \mathbf{f}(x_1, \dots, x_n) = t$

(Programs) $\ni p ::= d_1, \dots, d_n$

First order Language: semantics

- Call-by-value evaluation:

$$\frac{CBV[[e_i]]\vec{v} = v_i}{CBV[[c(e_1, \dots, e_n)]]\vec{v} = c(v_1, \dots, v_n)}$$

$$\frac{CBV[[e_i]]\vec{v} = v_i, \mathbf{f}(p_1, \dots, p_n) \rightarrow e, \sigma(p_i) = v_i \quad CBV[[\sigma(e)]]\vec{v} = v}{CBV[[\mathbf{f}(e_1, \dots, e_n)]]\vec{v} = v}$$

- The set *Values*: $Values \ni v ::= \mathbf{c} \mid \mathbf{c}(v_1, \dots, v_n) \quad \mathbf{c} \in \mathcal{C}$
- Error : **Err**
- Non-termination : \perp

Examples (1/2)

1. Multiplication

$$\underline{n} = s^n(0)$$

$$add(0, y) \rightarrow y$$

$$add(s(x), y) \rightarrow s(add(x, y))$$

$$mul(0, y) \rightarrow 0$$

$$mul(s(x), y) \rightarrow add(y, mul(x, y))$$

$$CBV \llbracket mul(x, y) \rrbracket (\underline{n}, \underline{m}) = \underline{n \times m}$$

Examples (2/2)

2. Exponential

$$d(0) \rightarrow 0$$

$$d(s(x)) \rightarrow s(s(d(x)))$$

$$\text{exp}(0) \rightarrow s(0)$$

$$\text{exp}(s(x)) \rightarrow d(\text{exp}(x))$$

$$CBV[\text{exp}(x)](\underline{n}) = \underline{2^n}$$

3. Non-termination

$$\mathfrak{f}(x) \rightarrow \mathfrak{f}(x)$$

$$CBV[\mathfrak{f}(x)](v) = \perp$$

Dependency Pairs (Arts et Giesl 96)

• $\langle f(\vec{p}), g(\vec{t}) \rangle$ dependency pair if $f(\vec{p}) \rightarrow C[g(\vec{t})]$

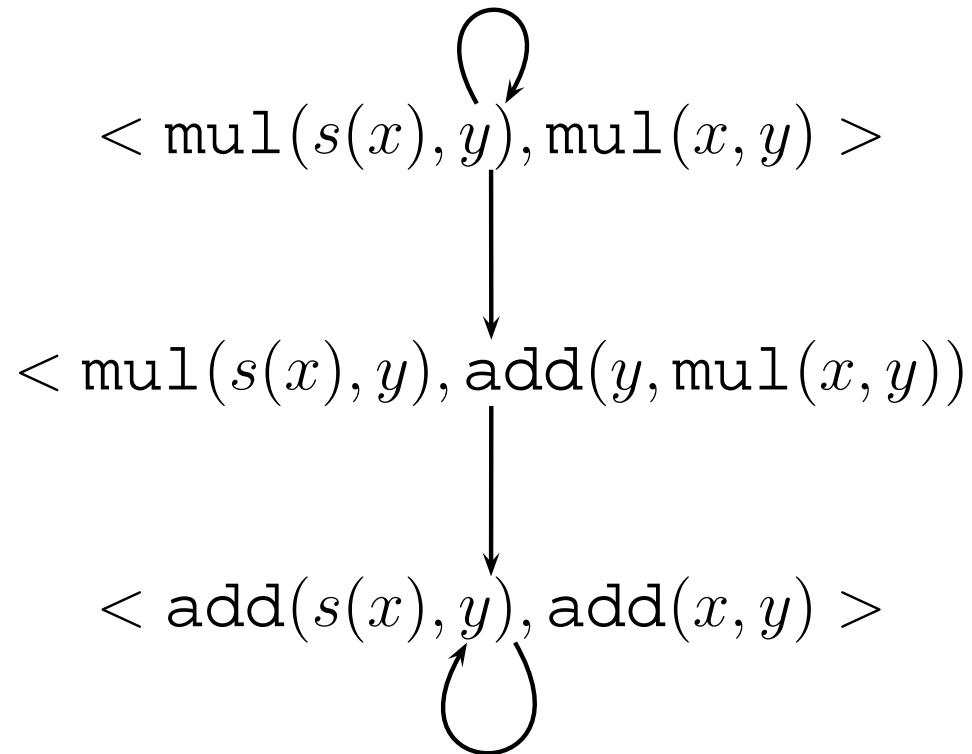
• Dependency graph:

1. States are dependency pairs

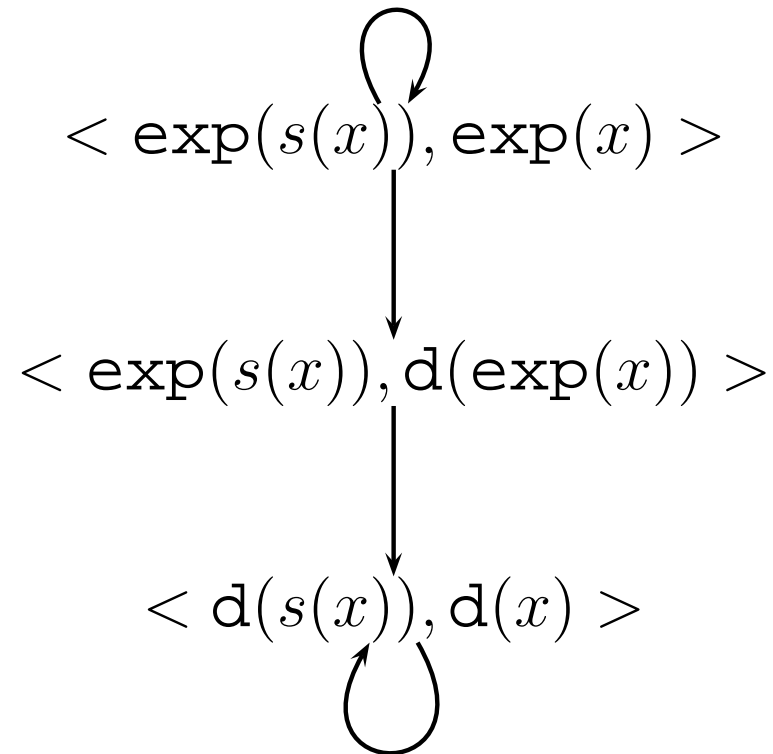
2. edges are defined by :

Given $u = \langle f_1(\vec{t}_1), f_2(\vec{t}_2) \rangle$ and $v = \langle f_3(\vec{t}_3), f_4(\vec{t}_4) \rangle$
 $u \longrightarrow v$ if $f_2 = f_3$

Examples : Multiplication (1/2)



Examples : Exponential (2/2)



Precedence

- $f \geq_{\mathcal{F}} g$ if $\langle f(\vec{p}), g(\vec{t}) \rangle$ dependency pairs
- $f \approx_{\mathcal{F}} g$ if f and g belong to the same cycle
- Precedence used in the construction of the bound.
- Exemple : $mul >_{\mathcal{F}} add$

Sup-interpretation

- Assignment θ such that for \mathbb{F} function ou constructor having a sup-interpretation, $\theta(\mathbb{F}) : \mathbb{R}^n \rightarrow \mathbb{R}$
- For $x \in \mathcal{X}$, we take $\theta(x) = X$
- We extend this assignment to terms by θ^* :

$$\theta^*(\mathbb{F}(\vec{v})) = \theta(\mathbb{F})(\theta^*(\vec{v}))$$

- $\theta^*(\bar{e}) = \max(\theta^*(e_1), \dots, \theta^*(e_n))$
- $\theta^*(\mathbf{Case} \bar{e} \text{ of } \bar{p}_1 \rightarrow e^1 \dots \bar{p}_\ell \rightarrow e^\ell) = \max(\theta^*(\bar{e}), \theta^*(e^1), \dots, \theta^*(e^\ell))$

Sup-interpretation

- A monotonic assignment is a sup-interpretation if it satisfies

$$\forall \vec{v} \text{ vector of values } \theta^*(g(\vec{v})) \geq \theta^*(CBV[[g]]\vec{v})$$

$$\theta^*(v) \geq |v| \text{ if } v \text{ value}$$

- Remark1: Quasi-interpretations are a special case of sup-interpretation (total, subterm property)
- Remark2: Sup-interpretations define a complexity measure (Blum).

Examples of sup-interpretation

1. Multiplication

- $\theta(\text{add}(x, y)) = X + Y$

- $\theta(\text{mul}(x, y)) = X \times Y$

2. Exponential

- $\theta(d(x)) = 2X$

- $\theta(\text{exp}(x)) = 2^X$

3. Non-termination

- $\theta(\text{f}(\vec{x}))$: any since $|\perp| = 0$

Fraternities

- A context C of a rule $f(\vec{p}) \rightarrow C[g_1(\vec{s}_1), \dots, g_n(\vec{s}_n)]$ is a fraternity if:
 - $\forall i \in [1, n], g_i \approx_{\mathcal{F}} f$
 - $\forall h \in C, f >_{\mathcal{F}} h$
- Example:
 - $mul(s(x), y) \rightarrow add(y, mul(x, y))$
 - $add(y, mul(x, y))$ is a fraternity with corresponding context $C[\diamond] = add(y, \diamond)$

Weight

- A weight ω is an assignment which ranges over function symbols and such:
 - For \mathbb{F} function symbol, $\omega_{\mathbb{F}}$ is weakly monotonic
 - For \mathbb{F} function symbol, $\omega_{\mathbb{F}}(\dots, X_i, \dots) \geq X_i$
- Examples: \max ou \sum
- Application: If $\omega_{\mathbb{F}} = \max$, then :

$$\omega_{\mathbb{F}}(\theta(x), \theta(y)) = \max(\theta(x), \theta(y))$$

Weight

- A weight is a quasi-interpretation in the sense that it has the same functional properties.
- A weight is a control point for the recursive calls
- Some criteria on Sup-interpretations + Weight will provide the polynomial space bound...

Friendly programs

A program P is friendly:

- if there are a polynomial sup-interpretation θ
- and a weight ω
- such that for every rule $\mathfrak{f}(\vec{p}) \rightarrow C[g_1(\vec{s}_1), \dots, g_n(\vec{s}_n)]$ with C fraternity:
- and every substitution σ

$$\omega_{\mathfrak{f}}(\theta^*(p_1\sigma), \dots, \theta^*(p_n\sigma)) \geq \omega_{g_i}(\theta^*(s_j^1\sigma), \dots, \theta^*(s_j^{L(j)}\sigma))$$

(condition I)

friendly programs

Where the fraternity $C[\mathfrak{g}_1(\vec{s}_1), \dots, \mathfrak{g}_n(\vec{s}_n)]$ verifies:

$$\theta^*(C[\diamond_1, \dots, \diamond_n]) = \max_{i=1..n}(\diamond_i + \alpha_i)$$

and if $\exists \sigma$ such that

$$\omega_{\mathfrak{f}}(\theta^*(p_1\sigma), \dots, \theta^*(p_n\sigma)) = \omega_{\mathfrak{g}_i}(\theta^*(s_j^1\sigma), \dots, \theta^*(s_j^{L(j)}\sigma))$$

then α_i is the null polynomial.

(condition II)

- Remark: We are in the case of recursive calls since $\mathfrak{f} \approx_{\mathcal{F}} \mathfrak{g}_i$

Multiplication: Condition I

$$\text{add}(s(x), y) \rightarrow s(\text{add}(x, y))$$

$$\text{mult}(s(x), y) \rightarrow \text{add}(y, \text{mult}(x, y))$$

$$\langle \text{add}(s(x), y), \text{add}(x, y) \rangle$$

$$\langle \text{mult}(s(x), y), \text{mult}(x, y) \rangle$$

● Condition I:

$$\omega_{\mathbb{F}}(\theta^*(p_1\sigma), \dots, \theta^*(p_n\sigma)) \geq \omega_{g_i}(\theta^*(s_j^1\sigma), \dots, \theta^*(s_j^{L(j)}\sigma))$$

$$\bullet \omega_{\text{add}}(\theta^*(s(x)), \theta^*(y)) > \omega_{\text{add}}(\theta^*(x), \theta^*(y))$$

$$\bullet \theta(s)(X) = X + 1 \text{ and } \omega_{\text{add}}(X, Y) = X + Y$$

Multiplication: Condition II

$$\text{add}(s(x), y) \rightarrow s(\text{add}(x, y))$$

$$\text{mult}(s(x), y) \rightarrow \text{add}(y, \text{mult}(x, y))$$

$$\langle \text{add}(s(x), y), \text{add}(x, y) \rangle$$

$$\langle \text{mult}(s(x), y), \text{mult}(x, y) \rangle$$

● Condition II:

$$\theta^*(C[\diamond_1, \dots, \diamond_n]) = \max_{i=1..n} (\diamond_i + \alpha_i)$$

● $C = s[\diamond]$ **et** $\theta^*(s(\diamond)) = \diamond + 1 = \max(\alpha + \diamond)$

● $C = \text{add}[y, \diamond]$ **et** $\theta^*(\text{add}(y, \diamond)) = Y + \diamond = \max(\alpha + \diamond)$

Theorem 1:

Given a friendly program \mathbf{p} , for every function symbol \mathfrak{f} , there is $P_{\mathfrak{f}}$ a polynomial such that:

For every \vec{v} , $|CBV[\mathfrak{f}]\vec{v}| \leq P_{\mathfrak{f}}(|\vec{v}|)$

if $CBV[\mathfrak{f}]\vec{v}$ is defined.

- Proof: We assign a polynomial $P_{\mathfrak{f}}$ to the program and check that it bounds the values added by the context plus the values added by the recursive calls.

Another example : Division

$\text{minus}(x, y) = \text{Case } x, y \text{ of } 0, z \rightarrow 0$

$s(z), 0 \rightarrow s(z)$

$s(u), s(v) \rightarrow \text{minus}(u, v)$

$\text{q}(x, y) = \text{Case } x, y \text{ of } 0, s(z) \rightarrow 0$

$s(z), s(u) \rightarrow s(\text{q}(\text{minus}(z, u), s(u)))$

Another example : Division

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$s(z), s(u) \rightarrow s(\text{q}(\text{minus}(z, u), s(u)))$

1. $\omega_{\text{minus}}(\theta^*(s(x)), \theta^*(s(y))) \geq \omega_{\text{minus}}(\theta(x), \theta(y))$

$$\omega_{\text{q}}(\theta^*(s(z)), \theta^*(s(u))) \geq \omega_{\text{q}}(\theta^*(\text{minus}(z, u)), \theta^*(s(u)))$$

Another example : Division

$\text{minus}(x, y) = \text{Case } x, y \text{ of } 0, z \rightarrow 0$

$s(z), 0 \rightarrow s(z)$

$s(u), s(v) \rightarrow \text{minus}(u, v)$

$\text{q}(x, y) = \text{Case } x, y \text{ of } 0, s(z) \rightarrow 0$

$s(z), s(u) \rightarrow s(\text{q}(\text{minus}(z, u), s(u)))$

1. $\omega_{\text{minus}}(\theta^*(s(x)), \theta^*(s(y))) \geq \omega_{\text{minus}}(\theta(x), \theta(y))$

$$\omega_{\text{q}}(\theta^*(s(z)), \theta^*(s(u))) \geq \omega_{\text{q}}(\theta^*(\text{minus}(z, u)), \theta^*(s(u)))$$

2. $\theta(s)(\diamond) = \diamond + \alpha$

Another example : Division

1. $\omega_{\text{minus}}(\theta^*(s(x)), \theta^*(s(y))) \geq \omega_{\text{minus}}(\theta(x), \theta(y))$

$$\omega_{\text{q}}(\theta^*(s(z)), \theta^*(s(u))) \geq \omega_{\text{q}}(\theta^*(\text{minus}(z, u)), \theta^*(s(u)))$$

2. $\theta(s)(\diamond) = \diamond + \alpha$

$$\theta(s)(X) = X + 1,$$

$$\omega_{\text{minus}}(X, Y) = \max(X, Y),$$

$$\omega_{\text{q}}(X, Y) = X + Y$$

$$\theta(\text{minus})(X, Y) = X$$

Exponential: an unfriendly program

$\text{double}(x) = \mathbf{Case } x \text{ of } 0 \rightarrow 0$

$s(y) \rightarrow s(s(\text{double}(y)))$

$\text{exp}(x) = \mathbf{Case } x \text{ of } 0 \rightarrow s(0)$

$s(y) \rightarrow \text{double}(\text{exp}(y))$

1. $\omega_{\text{double}}(\theta^*(s(y))) \geq \omega_{\text{double}}(\theta(y))$

$$\omega_{\text{exp}}(\theta^*(s(y))) \geq \omega_{\text{exp}}(\theta^*(y))$$

2. $\theta(\text{double})(\diamond) = \diamond + \alpha$ but $\theta(\text{double})(\diamond) \geq 2\diamond$

Call-tree

- If there is a rule $f(p_1, \dots, p_n) \rightarrow C[g(e_1, \dots, e_k)]$, a substitution σ such that:
 - $p_i\sigma = u_i$
 - $CBV[[e_j\sigma]] = v_j$
- Then we write $\langle f, u_1, \dots, u_n \rangle \xrightarrow{C[\diamond]} \langle g, v_1, \dots, v_k \rangle$
- The corresponding graph is called a call-tree of f over values u_1, \dots, u_n if $\langle f, u_1, \dots, u_n \rangle$ is its root.
- A call-tree gives a static view of an execution of a program.
- The states can be seen as stack frames

Theorem 2:

Given a friendly program \mathbf{p} , for every function symbol \mathfrak{f} , there is $P_{\mathfrak{f}}$ a polynomial such that for every state $\langle \mathfrak{g}, v_1, \dots, v_k \rangle$ of the call-tree of root $\langle \mathfrak{f}, u_1, \dots, u_n \rangle$:

$$\max_{i=1..k}(|v_i|) \leq P_{\mathfrak{f}}(|\vec{u}|)$$

even if the program is non-terminating.

- non-terminating programs
- programs over unbounded datas such as infinite streams

List of examples

- logarithm
 - division
 - reachability over graphs
 - elimination of duplicates in a list
-
- All these programs admit an S.I. but no Q.I.
 - However there are programs admitting QI and not friendly (In particular, programs over trees)

Open problems

- Try to capture the QI with a more general criteria
- Problem of synthesis (as Amadio did for the QI Amdio04)
- Try to find restriction in order to capture polynomial time